Quantum Reduced Loop Gravity II

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- The Idea
- Quantization and Symmetry Reduction
- Reduced Kinematical Hilbert Space: Cosmological LQG
- Constraints
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Motivation

General Relativity in Ashtekar variables

$$A_a^i(\mathbf{X}), E_i^a(\mathbf{X})$$

Symmetry reduction: homogeneity and isotropy

Cosmological models C, P

"LQG inspired" quantization

Only

homogeneous

Cosmologies

Ashtekar, Agullo, Barrau, Bojowald, Campiglia, Corichi, Giesel, Hofmann, Grain, Henderson, Kaminski, Lewandowski, Mena Marugan, Nelson, Pawlowski, Pullin, Singh, Sloan, Taveras, Thiemann,, Winkler, Wilson-Ewing



Motivation

General Relativity in Ashtekar variables



Symmetry reduction: Homogeneity, isotropy, inohomogeneities

Which cosmology we get from the full theory? Beyond homogeneity ? The Idea

Look at the <u>inhomogeneous</u> line element in the BKL conjecture Belinski-Khalatnikov-Lifshitz '70 :

$$ds^2 = N^2(t)dt^2 - e^{2\alpha(t,x)}(e^{2\beta(t,x)})_{ij}\,\omega^i\otimes\omega^j$$

 α Describes the Volume

 β (diagonal matrix, Tr $\beta = 0$) Describes local anisotropies ω one forms corresponding to an homogeneous
 Bianchi model

GOAL:

find a quantum symmetry reduction of LQG compatible with this line element

If we remove the spatial dependence from α and β , we can recover generic Bianchi models

Reduced Ashtekar variables in the hypotesis of the BKL conjecture

 $U(1)_i$

paths lead to the product of three

independent U(1)_i

Cosmological LQG

GOAL:

Implement on the SU(2) Kinematical Hilbert space of LQG the classical reduction:

$$A_a^i = c_i(t, x)\omega_a^i$$
$$E_i^a = p^i(t, x)\omega\omega_i^a$$
$$\{p^i(x, t), c_j(y, t)\} = 8\pi G\gamma\delta_j^i\delta^3(x - y)$$

First truncation: we restrict the holonomies to curves along edges e_i parallel to fiducial ω_i^a vectors

The SU(2) classical holonomies associated to the reduced variables are

 ${}^{R}_{-}h^{j}_{e_{i}} = \exp\left(i\alpha^{i}\tau_{i}\right)$

$${}^{R}h_{e_{i}}^{j} = P(e^{i\int_{e_{i}}c^{i}\omega_{a}^{i}dx^{a}(s)\tau_{i}}) \sim$$

NO sum over i

Holonomy belong to the U(1) subgroup generated by τ_i

Consider fluxes across surfaces $x^a(u,v)$ with <u>normal vectors</u> parallel to the fiducial ones



The classical reduction implies

$$E_i(S^k) = \int E_i^a \frac{1}{\omega} \omega_a^k du dv = \delta_i^k \int p_i \frac{1}{\omega} du dv$$

For consistency only the diagonal part of the matrix $E_i(S^j)$ is non vanishing

Second class with the Gauss constraint

$$\chi_i = \sum_{l,k} \epsilon_{il} \,^k E_k(S^l) = 0$$

How to implement the reduction on the holonomies and consistently impose $\chi_i=0$?

Strategy: Mimic the spinfoam procedure

Impose the <u>second class constraint weakly</u> to find a "Physical Hilbert space" Engle, Pereira, Rovelli, Livine '07- '08

Imposing a Master constraint strongly on the SU(2) holonomies:

$$\chi^{2} = \sum_{i} \chi_{i} \chi_{i} = \sum_{i,m,k,l} [\delta^{im} \delta_{kl} E_{i}(S^{k}) E_{m}(S^{l}) - E_{i}(S^{k}) E_{k}(S^{i})]$$

$$\chi^2 h_{e_i}^j = (8\pi\gamma l_P^2)^2 (\tau^2 - \tau_i \tau_i) h_{e_i}^j = 0$$

Different i for each direction

To solve it is convenient to introduce SU(2) coherent states

SU(2) coherent states

$$|j, \vec{u} \rangle = D^{j}(\vec{u})|j, j\rangle = \sum_{m} |j, m \rangle D^{j}(\vec{u})_{mj}$$

The Master constraint condition acting at the endpoint (the conjugate condition at the starting point):

 $\chi^2 D^j(g)|j,\vec{u}>=D^j(g)(\tau^2-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau})^2)|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau}))|j,\vec{u}>=D^j(g)(j(j+1)-(\vec{e_i}\cdot\vec{\tau}))|j,\vec{u}>=D^j($

Using the property $ec{v}\cdotec{ au}|j,ec{v}>=j|j,ec{v}>$

If $\vec{e_i} = \vec{u}$ in the large j limit up to L_p corrections the basis element will satisfy:

 $\chi^2 D^j(g) | j, \vec{u} >= 0$ Reduced basis Elements

 $\langle j, \vec{e_i} | D^j(g) | j, \vec{e_i} \rangle$

There is a natural way of embedding U(1) cylindrical functions in SU(2) ones:

Projected spinnetworks (Alexandrov, Livine '02) with the Dupuis-Livine map (Dupuis Livine '10)

These SU(2) functions have the remarkable property that <u>they are completely determined</u> by their restriction to their U(1) subgroup

$$\tilde{\psi}(g)|_{U(1)} = \psi$$

If we consider <u>projected functions</u> defined over the edge e_i choosing the subgroup $U(1)_i$ as the one generated by τ_i

The Master constraint equation selects the degree of the map:

$$|n_i| = j(n)$$

The strong quadratic condition implies the linear one weakly (restriction to symmetric matrix) !

$$<\tilde{\psi}'_{i}|E_{k}(S^{l})|\tilde{\psi}_{i}>=8\pi\gamma l_{P}^{2}\sum_{j,j'}\psi^{j'}_{e_{i}}\int dg^{i}D^{j'}_{j'j'}(g)\tau_{k}{}^{i}D^{j}_{jj}(g)\psi^{j}_{e_{i}}=0,\qquad (k\neq 0)$$

The quantum states associated with an edge e_i are entirely determined by their projection into the subspace with maximum magnetic numbers along the internal direction i

$$\psi_{e_i} = \tilde{\psi}(g)_{e_i}|_{U(1)_i} = \sum_j e^{i\theta^i j} \psi_{e_i}^j = \sum_j i < j, j |^R h_{e_i}^j |j, j > i \psi_{e_i}^j$$

The action of fluxes $E_l(S^k)$ on the reduced space is nonvanishing only for l = k = i

$$E_i(S^i)\tilde{\psi}_{e_i} = 8\pi\gamma l_P^2 \sum_j jD_{jj}^j \psi_{e_i}^j$$

This is how we find in the SU(2) quantum theory the classical reduction

$$A_a^i = c_i(t, x)\omega_a^i$$
 $E_i^a = p^i(t, x)\omega\omega_i^a$

$$\{p^i(x,t),c_j(y,t)\} = 8\pi G\gamma \delta^i_j \delta^3(x-y)$$

SL(2,C) basis elements

SU(2) basis elements

$$\begin{split} \langle g | p, k, j, m, j', m' \rangle &= D_{jm,j'm'}^{p,k}(g) & \longrightarrow & \langle g | j, m, r \rangle = D_{mr}^{j}(g) \\ \tilde{\psi}(g) &= \sum_{jmn} d_j \, \psi_{jmn} \, D_{jm,jn}^{p(j),j}(g) & \longrightarrow & \tilde{\psi}(g)_{e_i} = \sum_{n_i} {}^i D_{m=n_i \, r=n_i}^{j(n_i)}(g) \psi_{e_i}^{n_i} \\ \text{Linear simplicity constraint} \end{split}$$

$$\vec{K} + \gamma \vec{L} = 0$$

Quadratic part of the constraint imposed strongly:

$$\left(2\gamma C_1 - (\gamma^2 - 1)C_2\right)|\tilde{\psi}\rangle = 0$$

 $p = \gamma k$

Weakly satisfied in the large limit

 $\langle \tilde{\psi} | \vec{K} + \gamma \vec{L} | \tilde{\psi}' \rangle = 0$

Select k = j

$$g|_{\mathcal{K}} = D_{jm,jn}^{\gamma j,j}(g) = \int_{SU(2)} dh \ K(g,h) \ D_{mn}^{j}(h)$$

$$\tau^k h^j_{e_i} = 0 \quad \forall k \neq i$$

$$rac{(au^2- au_i au_i)h_{e_i}^j=0}{ ext{Select j(n)=n}}$$

Only one condition (SU(2) has only one parameter label for the irrep.)

Weakly satisfied in the large limit

$$\langle \tilde{\psi}_i' | E_k(S^l) | \tilde{\psi}_i \rangle = 0$$

$$g|_{\mathcal{K}} = {}^{i}D_{jj}^{|j|}(g)$$

If we define a Projector P_{γ} on Physical reduced states:

The projector P_{γ} acting on ψ_{Γ} SU(2) cylindrical functions defined on general Graphs Γ :

• <u>Restrict the Graphs</u> to be part of a cubical lattice



 Select the states belonging to the SU(2) subspace where <u>our constraint conditions</u> <u>hold weakly</u>:

$$\tilde{\psi}(g)_{e_i} = \sum_{n_i} {}^i D_{m=n_i r=n_i}^{j(n_i)}(g) \psi_{e_i}^{n_i}$$



Implementing



The reduced states will be of the form :

$$\langle h|\Gamma, j_e, x_v\rangle_R = \prod_{v\in\Gamma} \prod_{e\in\Gamma} \langle \mathbf{j_i}, \mathbf{x}|\mathbf{j_i}, \mathbf{\vec{u}}_i \rangle \cdot {}^i D^{j_{e_i}}(h_{e_i})_{j_i j_i}$$

Projection on the intertwiner base of the Livine Speziale Intertwiner: Livine, Speziale '07



The Inhomogenous sector



Homogeneous and anisotropic sector



Homogeneous and Isotropic sector





Equivalence class of graphs that preserve the cellular structure:





The regularized Euclidean constraint in the full theory reads:

T. Thiemann '96-'98

$$H^m_{\ \ \square} \ [N] := \frac{N(\mathfrak{n})}{N_m^2} \ \epsilon^{ijk} \operatorname{Tr} \Big[h^{(m)}_{\alpha_{ij}} h^{(m)}_{s_k} \big\{ h^{(m)-1}_{s_k}, V \big\} \Big]$$

We regularize à la Thiemann, but using only elements of the reduced space:

$${}^{R}H^{m}_{\ \square}\ [N] := \frac{N(\mathfrak{n})}{N_{m}^{2}} \ \epsilon^{ijk} \operatorname{Tr} \Big[{}^{R}h^{(m)R}_{\alpha_{ij}} h^{(m)}_{s_{k}} \big\{ {}^{R}h^{(m)-1}_{s_{k}}, V \big\} \Big]$$

Action of the operator

on a tri-valent node:









Large j limit "seems":

$$\frac{c_1c_2}{p_3} + \frac{c_1c_3}{p_2} + \frac{c_2c_3}{p_1} = 0$$

News

Semiclassical limit

$$\begin{split} \Psi_{\Gamma,H_l}(h_l) &= \int \prod_n dg_n \, \prod_l K_{\alpha_l}(h_l, \, g_{s(l)} \, H_l \, g_{t(l)}^{-1}) \\ \end{split}$$
Heat Kernel
oherent states
$$H_l &= h_l \, \exp(i \frac{\alpha_l E_l}{8\pi G \hbar \gamma}) \end{split}$$

SL(2,C) element coding classical data

Hall, Thiemann, Winkler, Sahlmann, Bahr

$$\Psi_{H_l}(h_l) = \sum_{j_l, i_n} \psi_{H_l}(j_l, i_n) \Psi_{j_l, i_n}(h_l)$$

intertwiner base

Large distance asymptotic behaviour Bianchi Magliaro Perini



 $j_0 = \frac{|E|}{8\pi G\hbar\gamma}$

 $\xi \sim K = c$

Project in our reduced space the coherent states

 $P_{\chi}|\Psi_{H_l}\rangle = |\Psi_{H_l}\rangle_R$





This analysis opens the way to

- Study the Physical solutions on the Dual Diff invariant Space and eventually construct a Physical Scalar Product
- Add matter as a clock: Big Bounce ? QFT on quantum spacetime ?
- Link to LQC ?
- Spinfoam Cosmology? *Bianchi, Krajewski, Rovelli, Vidotto*
- Something Different ?

(In the homogeneous anisotropic case the scale factors are not independent (Clebsh conditions) and <u>even less</u> dynamically) Isotropization mechanism?

• <u>Arena for the canonical theory</u>:

AQG, Master constraint, deparametrized theories.. Computable!