

Polymerization and saddle point approximation issues in dilatonic black holes: a toy model

Saeed Rastgoo
in collaboration with
Hugo Morales-Técotl, Daniel Humberto Orozco

UAM-I, Mexico City

Third EFI, Tux, Austria, February 20, 2015

Outline

- Grand scheme of the project: dilatonic models using LQG.

Outline

- Grand scheme of the project: dilatonic models using LQG.
- Problem of access to semiclassical approximation in path integral method.

Outline

- Grand scheme of the project: dilatonic models using LQG.
- Problem of access to semiclassical approximation in path integral method.
- Toy model: can polymerization be an alternative solution? and its implications?

Outline

- Grand scheme of the project: dilatonic models using LQG.
- Problem of access to semiclassical approximation in path integral method.
- Toy model: can polymerization be an alternative solution? and its implications?
- Lessons learned from the toy model.

Introduction: the grand plan

Motivation for 2D dilatonic models

Generic action of 2D dilatonic models

$$S = - \int_{\mathcal{M}} d^2x \sqrt{-g} [\Phi R - U(\Phi) \nabla_a \Phi \nabla^a \Phi - 2V(\Phi)]$$

Motivation for 2D dilatonic models

Generic action of 2D dilatonic models

$$S = - \int_{\mathcal{M}} d^2x \sqrt{-g} [\Phi R - U(\Phi) \nabla_a \Phi \nabla^a \Phi - 2V(\Phi)]$$

Why dilatonic models?

Motivation for 2D dilatonic models

Generic action of 2D dilatonic models

$$S = - \int_{\mathcal{M}} d^2x \sqrt{-g} [\Phi R - U(\Phi) \nabla_a \Phi \nabla^a \Phi - 2V(\Phi)]$$

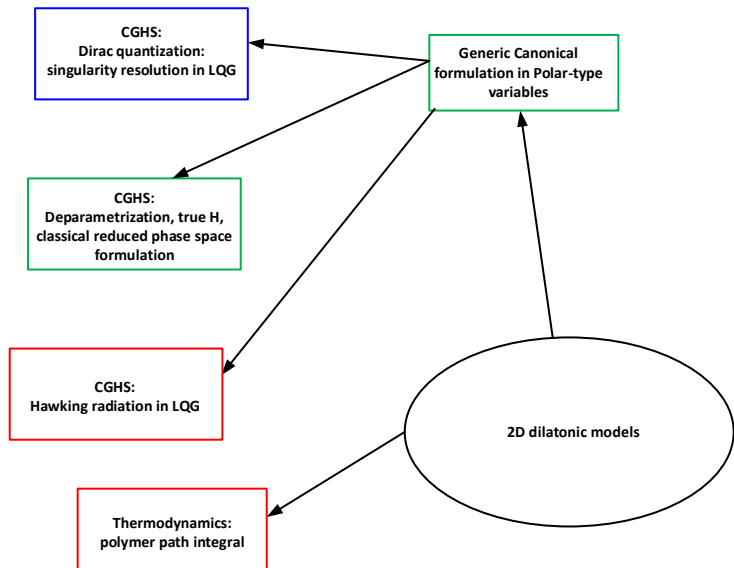
Why dilatonic models?

- Alternatives to dark matter/ Λ
- Cosmology (inflaton)
- Equivalent to some symmetry reduced models (3+1 sph. symmet.)
- Chameleon theories
- Interesting BH properties
- Some (like CGHS) classically completely solvable
- Extensive work in string and QFT in CST community. May be able to do some comparisons.
- ...

Some important submodels

Model	$U(\Phi)$	$V(\Phi)$
Schwarzschild	$-(2\Phi)^{-1}$	$-(2G_4)^{-1}$
CGHS	0	$-\frac{\lambda}{2}$
Jackiw-Teitelboim	0	$-\Lambda\Phi$
Witten BH	Φ^{-1}	$-\frac{\lambda^2}{2}\Phi$
Liouville Gravity	a	$be^{\alpha\Phi}$
Rindler Ground State	$-a\Phi^{-1}$	$-\frac{1}{2}B\Phi^a$
...

Grand scheme of the dilatonic project



The problem: Access to the semiclassical approximation

2D dilatonic models (black holes)

The main class: generic 2D dilatonic

$$S = - \int_{\mathcal{M}} d^2x \sqrt{-g} [\Phi R - U(\Phi) \nabla_a \Phi \nabla^a \Phi - 2V(\Phi)] - \underbrace{\frac{1}{2} \int_{\partial\mathcal{M}} dx \sqrt{q} \Phi K}_{\text{GHY}}$$

Gibbons-Hawking-York (GHY) boundary term: removing necessity of introducing Neumann boundary conditions $\delta(\partial_a g_{bc}) = 0$.

Thermodynamics & access to semiclassical approx.

Study thermodynamics using Euclidean path integral

$$\mathcal{Z} = \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{\hbar} S_E[g, \Phi]\right)$$

Path integral \approx Partition function in canonical ensemble.

Thermodynamics & access to semiclassical approx.

Study thermodynamics using Euclidean path integral

$$\mathcal{Z} = \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{\hbar} S_E[g, \Phi]\right)$$

Path integral \approx Partition function in canonical ensemble.

Semiclassical (i.e. saddle point) approximation: dominated by $\delta S = 0$.

Thermodynamics & access to semiclassical approx.

Study thermodynamics using Euclidean path integral

$$\mathcal{Z} = \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{\hbar} S_E[g, \Phi]\right)$$

Path integral \approx Partition function in canonical ensemble.

Semiclassical (i.e. saddle point) approximation: dominated by $\delta S = 0$.

- Physics: most contributions coming from classical path

Thermodynamics & access to semiclassical approx.

Study thermodynamics using Euclidean path integral

$$\mathcal{Z} = \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{\hbar} S_E[g, \Phi]\right)$$

Path integral \approx Partition function in canonical ensemble.

Semiclassical (i.e. saddle point) approximation: dominated by $\delta S = 0$.

- Physics: most contributions coming from classical path
- Math: given

$$S[g_{cl} + \delta g, \Phi_{cl} + \delta \Phi] = S[g_{cl}, \Phi_{cl}] + \delta S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi] + \frac{1}{2} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi] + \dots$$

$\exp\left(-\frac{1}{\hbar} S[g, \Phi]\right)$ gets most important contribution from the minimum of S .

Thermodynamics & access to semiclassical approx.

If

- S is finite
- $\delta S = 0$
- $\delta^2 S > 0$ (minimum)

$$\mathcal{Z} \approx \exp\left(-\frac{1}{\hbar} S[g_{cl}, \Phi_{cl}]\right) \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi]\right)$$

gives the semiclassical approximation

Thermodynamics & access to semiclassical approx.

If

- S is finite
- $\delta S = 0$
- $\delta^2 S > 0$ (minimum)

$$\mathcal{Z} \approx \exp\left(-\frac{1}{\hbar} S[g_{cl}, \Phi_{cl}]\right) \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi]\right)$$

gives the semiclassical approximation

All looks cool except ...

Thermodynamics & access to semiclassical approx.

If

- S is finite
- $\delta S = 0$
- $\delta^2 S > 0$ (minimum)

$$\mathcal{Z} \approx \exp\left(-\frac{1}{\hbar} S[g_{cl}, \Phi_{cl}]\right) \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi]\right)$$

gives the semiclassical approximation

All looks cool except ... it is not!

Thermodynamics & access to semiclassical approx.

If

- S is finite
- $\delta S = 0$
- $\delta^2 S > 0$ (minimum)

$$\mathcal{Z} \approx \exp\left(-\frac{1}{\hbar} S[g_{cl}, \Phi_{cl}]\right) \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta\Phi]\right)$$

gives the semiclassical approximation

All looks cool except ... it is not!

1- $\delta S \neq 0$ for all field variations that preserve the path integral boundary conditions: collapse of saddle point approximation

$$\delta S \Big|_{\text{on-shell}} \sim \int_{\partial\mathcal{M}} dx \sqrt{q} \left[\Xi^{ab} \delta q_{ab} + \Upsilon_{\Phi} \delta\Phi \right]$$

even though $\delta q_{ab} \rightarrow 0$ and $\delta\Phi \rightarrow 0$ at $\partial\mathcal{M}$, the coefficients Ξ^{ab} and/or Υ_{Φ} diverge so rapidly $\implies \delta S \not\rightarrow 0$. (details later slides)

Thermodynamics & access to semiclassical approx.

If

- S is finite
- $\delta S = 0$
- $\delta^2 S > 0$ (minimum)

$$\mathcal{Z} \approx \exp\left(-\frac{1}{\hbar} S[g_{cl}, \Phi_{cl}]\right) \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi]\right)$$

gives the semiclassical approximation

All looks cool except ... it is not!

$$2- S \Big|_{\text{on-shell}} \rightarrow \infty$$

Thermodynamics & access to semiclassical approx.

If

- S is finite
- $\delta S = 0$
- $\delta^2 S > 0$ (minimum)

$$\mathcal{Z} \approx \exp\left(-\frac{1}{\hbar} S[g_{cl}, \Phi_{cl}]\right) \int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi]\right)$$

gives the semiclassical approximation

All looks cool except ... it is not!

3- Gaussian integral diverges (not always)

$$\int \mathcal{D}g \mathcal{D}\Phi \exp\left(-\frac{1}{2\hbar} \delta^2 S[g_{cl}, \Phi_{cl}; \delta g, \delta \Phi]\right) \rightarrow \infty$$

Common solutions vs. our proposed solutions and strategy

Common solutions:

1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)

Common solutions vs. our proposed solutions and strategy

Common solutions:

- 1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)
- 2- Add a Hamilton-Jacobi counter-term: resolves both; correct thermodynamics

Common solutions vs. our proposed solutions and strategy

Common solutions:

- 1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)
 - 2- Add a Hamilton-Jacobi counter-term: resolves both; correct thermodynamics
-

Our speculation: polymerization may cure things. Even if not, any positive effect?

Common solutions vs. our proposed solutions and strategy

Common solutions:

- 1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)
 - 2- Add a Hamilton-Jacobi counter-term: resolves both; correct thermodynamics
-

Our speculation: polymerization may cure things. Even if not, any positive effect?

Two cases may happen by polymerization:

- 1- It eliminates the need to add a boundary counter-term.

Common solutions vs. our proposed solutions and strategy

Common solutions:

- 1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)
 - 2- Add a Hamilton-Jacobi counter-term: resolves both; correct thermodynamics
-

Our speculation: polymerization may cure things. Even if not, any positive effect?

Two cases may happen by polymerization:

- 1- It eliminates the need to add a boundary counter-term.
- 2- It does not eliminate the counter-term but modifies it.

Common solutions vs. our proposed solutions and strategy

Common solutions:

- 1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)
 - 2- Add a Hamilton-Jacobi counter-term: resolves both; correct thermodynamics
-

Our speculation: polymerization may cure things. Even if not, any positive effect?

Two cases may happen by polymerization:

- 1- It eliminates the need to add a boundary counter-term.
- 2- It does not eliminate the counter-term but modifies it.

In both cases what corrections to thermodynamics of the BH.

Common solutions vs. our proposed solutions and strategy

Common solutions:

- 1- Ad hoc “background subtraction”: resolves $S \rightarrow \infty$, not $\delta S \neq 0$; does not correctly reproduce some thermodynamics (consistency with the first law)
 - 2- Add a Hamilton-Jacobi counter-term: resolves both; correct thermodynamics
-

Our speculation: polymerization may cure things. Even if not, any positive effect?

Two cases may happen by polymerization:

- 1- It eliminates the need to add a boundary counter-term.
- 2- It does not eliminate the counter-term but modifies it.

In both cases what corrections to thermodynamics of the BH.

Strategy: analyze a simple toy model first.

Several analog models with the same problems (half binding potential).

One very simple one: particle in an inverse square potential.

A bit more details of the problem in dilatonic black holes and common solutions

Divergence of $S_{\text{on-shell}}$ of the black hole - 1

Solutions to EOM posses at least one Killing with orbits being curves of $\Phi = \text{const.}$

Divergence of $S_{\text{on-shell}}$ of the black hole - 1

Solutions to EOM possess at least one Killing with orbits being curves of $\Phi = \text{const.}$

Choose a gauge (diagonal metric). Solutions can be written as (can also be done gauge invariant)

$$ds^2 = \xi(r)d\tau^2 + \frac{1}{\xi(r)}dr^2, \quad \Phi = \Phi(r)$$

where

$$\partial_r \Phi = e^{-Q(\Phi)} \quad \xi(r) = w(\Phi)e^{Q(\Phi)} \left(1 - \frac{2M}{w(\Phi)}\right)$$

with

$$Q(\Phi) = \int^\Phi d\tilde{\Phi} U(\tilde{\Phi}) \quad w(\Phi) = \int^\Phi d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

Divergence of $S_{\text{on-shell}}$ of the black hole - 1

Solutions to EOM possess at least one Killing with orbits being curves of $\Phi = \text{const.}$

Choose a gauge (diagonal metric). Solutions can be written as (can also be done gauge invariant)

$$ds^2 = \xi(r)d\tau^2 + \frac{1}{\xi(r)}dr^2, \quad \Phi = \Phi(r)$$

where

$$\partial_r \Phi = e^{-Q(\Phi)} \quad \xi(r) = w(\Phi)e^{Q(\Phi)} \left(1 - \frac{2M}{w(\Phi)}\right)$$

with

$$Q(\Phi) = \int^\Phi d\tilde{\Phi} U(\tilde{\Phi}) \quad w(\Phi) = \int^\Phi d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

Killing ∂_τ with norm $\sqrt{\xi(r)}$. If $\xi(r) = 0 \implies$ Killing horizon (BH). Then $w_h = 2M$.

Divergence of $S_{\text{on-shell}}$ of the black hole - 2

Boundary conditions w.r.t. Φ

$$\Phi_h \leq \Phi < \infty \implies \underbrace{w_h}_{2M} \leq w < \underbrace{w_\infty}_{\infty}$$

thus the on shell action

$$S \Big|_{cl} = -\beta (w_\infty - w_h) - 2\Phi_h$$

blows up (see more clear later in toy model).

Divergence of $S_{\text{on-shell}}$ of the black hole - 2

Boundary conditions w.r.t. Φ

$$\Phi_h \leq \Phi < \infty \implies \underbrace{w_h}_{2M} \leq w < \underbrace{w_\infty}_\infty$$

thus the on shell action

$$S \Big|_{cl} = -\beta (w_\infty - w_h) - 2\Phi_h$$

blows up (see more clear later in toy model).

Background subtraction: take out $w_\infty \implies$ wrong thermodynamics.

Problem with first variation of the action - 1

The statement that $\delta S \neq 0$ for all variations of fields that preserve boundary conditions, may seem odd...

Problem with first variation of the action - 1

The statement that $\delta S \neq 0$ for all variations of fields that preserve boundary conditions, may seem odd...

Isn't Gibbons- Hawking-York (GHY) term there to make variational principle well-defined?

Problem with first variation of the action - 1

The statement that $\delta S \neq 0$ for all variations of fields that preserve boundary conditions, may seem odd...

Isn't Gibbons- Hawking-York (GHY) term there to make variational principle well-defined?

GHY only ensures that fields only need Dirichlet conditions at $\partial\mathcal{M}$. It does not guarantee that the boundary term in δS vanishes for arbitrary $\delta\gamma_{ab}$ and $\delta\Phi$ that preserve these boundary conditions.

Problem with first variation of the action - 2

δS on previous solutions

$$\delta S = \int d\tau \left[-\frac{1}{2} \partial_r \Phi \delta \xi + \left(U(\Phi) \xi(\Phi) \partial_r \Phi - \frac{1}{2} \partial_r \xi \right) \delta \Phi \right]$$

Problem with first variation of the action - 2

δS on previous solutions

$$\delta S = \int d\tau \left[-\frac{1}{2} \partial_r \Phi \delta \xi + \left(U(\Phi) \xi(\Phi) \partial_r \Phi - \frac{1}{2} \partial_r \xi \right) \delta \Phi \right]$$

Take the first term. By EOM

$$\partial_r \Phi = e^{-Q(\Phi)}.$$

If on $\partial \mathcal{M}$ we have $\xi \rightarrow \text{const.}$, we may assume $\delta \xi \rightarrow 0$.

Problem with first variation of the action - 2

δS on previous solutions

$$\delta S = \int d\tau \left[-\frac{1}{2} \partial_r \Phi \delta \xi + \left(U(\Phi) \xi(\Phi) \partial_r \Phi - \frac{1}{2} \partial_r \xi \right) \delta \Phi \right]$$

Take the first term. By EOM

$$\partial_r \Phi = e^{-Q(\Phi)}.$$

If on $\partial \mathcal{M}$ we have $\xi \rightarrow \text{const.}$, we may assume $\delta \xi \rightarrow 0$.

But if $\xi_{\Phi \rightarrow \infty} \rightarrow \infty$ on $\partial \mathcal{M}$, we cannot assume $\delta \xi \rightarrow 0$. Then we should appeal to general solutions and find the behavior of $\delta \xi$. It turns out

$$\delta \xi = e^{Q(\Phi)} \delta M$$

Problem with first variation of the action - 2

δS on previous solutions

$$\delta S = \int d\tau \left[-\frac{1}{2} \partial_r \Phi \delta \xi + \left(U(\Phi) \xi(\Phi) \partial_r \Phi - \frac{1}{2} \partial_r \xi \right) \delta \Phi \right]$$

Take the first term. By EOM

$$\partial_r \Phi = e^{-Q(\Phi)}.$$

If on $\partial \mathcal{M}$ we have $\xi \rightarrow \text{const.}$, we may assume $\delta \xi \rightarrow 0$.

But if $\xi_{\Phi \rightarrow \infty} \rightarrow \infty$ on $\partial \mathcal{M}$, we cannot assume $\delta \xi \rightarrow 0$. Then we should appeal to general solutions and find the behavior of $\delta \xi$. It turns out

$$\delta \xi = e^{Q(\Phi)} \delta M$$

The first term on δS becomes

$$\int d\tau \delta M \neq 0$$

i.e. solutions do not extremize the action for generic variations $\delta \xi$ that preserve the boundary conditions on ξ .

Counter-term method

The common solution: add a boundary counter term that is the solution to the Hamilton-Jacobi equation of the on-shell action

$$S_{CT} = - \int_{\partial\mathcal{M}} d\tau \sqrt{q} \left(\sqrt{e^{-Q(\Phi)} (w(\Phi) + c)} \right).$$

Counter-term method

The common solution: add a boundary counter term that is the solution to the Hamilton-Jacobi equation of the on-shell action

$$S_{CT} = - \int_{\partial\mathcal{M}} d\tau \sqrt{q} \left(\sqrt{e^{-Q(\Phi)} (w(\Phi) + c)} \right).$$

The final action becomes

$$S_f = S + S_{CT}$$

where $S|_{cl} < \infty$ and $\delta S = 0$.

Counter-term method

The common solution: add a boundary counter term that is the solution to the Hamilton-Jacobi equation of the on-shell action

$$S_{CT} = - \int_{\partial\mathcal{M}} d\tau \sqrt{q} \left(\sqrt{e^{-Q(\Phi)} (w(\Phi) + c)} \right).$$

The final action becomes

$$S_f = S + S_{CT}$$

where $S|_{cl} < \infty$ and $\delta S = 0$.

Essentially does something similar to GHY term: removes the need to consider boundary conditions when the fields $\Theta \rightarrow \infty$ on $\partial\mathcal{M}$, i.e $\delta\Theta \neq 0$.

Counter-term effect on thermodynamics

Thermodynamics is affected: Helmholtz free energy

$$F = T(\Phi)S_f$$

with $T(\Phi)$ the Tolman factor: proper local temperature related to β^{-1} (Hawking) temperature at infinity by a redshift factor

$$T(\Phi) = \frac{1}{\sqrt{\xi(\Phi)}}\beta^{-1}$$

Counter-term effect on thermodynamics

Thermodynamics is affected: Helmholtz free energy

$$F = T(\Phi)S_f$$

with $T(\Phi)$ the Tolman factor: proper local temperature related to β^{-1} (Hawking) temperature at infinity by a redshift factor

$$T(\Phi) = \frac{1}{\sqrt{\xi(\Phi)}}\beta^{-1}$$

Entropy:

$$S = -\left.\frac{\partial F}{\partial T(\Phi)}\right|_{\Phi_c} = \frac{A}{4G_{\text{eff}}}, \quad G_{\text{eff}} = \frac{G_2}{\Phi_h}$$

Φ_c value of the dilaton field at

the location of the cavity wall in contact with a thermal reservoir. Φ_h at horizon.

Counter-term effect on thermodynamics

Thermodynamics is affected: Helmholtz free energy

$$F = T(\Phi)S_f$$

with $T(\Phi)$ the Tolman factor: proper local temperature related to β^{-1} (Hawking) temperature at infinity by a redshift factor

$$T(\Phi) = \frac{1}{\sqrt{\xi(\Phi)}}\beta^{-1}$$

Entropy:

$$S = -\left.\frac{\partial F}{\partial T(\Phi)}\right|_{\Phi_c} = \frac{A}{4G_{\text{eff}}}, \quad G_{\text{eff}} = \frac{G_2}{\Phi_h}$$

Φ_c value of the dilaton field at

the location of the cavity wall in contact with a thermal reservoir. Φ_h at horizon.

The same way: chemical potential, internal energy, specific heat, enthalpy, etc.

Counter-term effect on thermodynamics

Thermodynamics is affected: Helmholtz free energy

$$F = T(\Phi)S_f$$

with $T(\Phi)$ the Tolman factor: proper local temperature related to β^{-1} (Hawking) temperature at infinity by a redshift factor

$$T(\Phi) = \frac{1}{\sqrt{\xi(\Phi)}}\beta^{-1}$$

Entropy:

$$S = -\left.\frac{\partial F}{\partial T(\Phi)}\right|_{\Phi_c} = \frac{A}{4G_{\text{eff}}}, \quad G_{\text{eff}} = \frac{G_2}{\Phi_h}$$

Φ_c value of the dilaton field at

the location of the cavity wall in contact with a thermal reservoir. Φ_h at horizon.

The same way: chemical potential, internal energy, specific heat, enthalpy, etc.

As mentioned: does polymerization change any of these?

The toy model: Problems and lessons

Analog problems in the toy model

A (class of) surprisingly simple model has the same problems: for

$$S = \int dt \left(\frac{\dot{q}^2}{2} - \frac{1}{q^2} \right)$$

the on-shell action becomes

$$S[q_{cl}] = \frac{1}{2} q_{cl} \dot{q}_{cl} \Big|_0^\infty + \text{finite}$$

Due to the form of potential, $q \rightarrow \infty$ and $\dot{q} \rightarrow \text{constant}$.

Similar to $w \rightarrow \infty$ to the form of dilaton potential, leading to $S \rightarrow \infty$ in BH case.

Analog problems in the toy model

A (class of) surprisingly simple model has the same problems: for

$$S = \int dt \left(\frac{\dot{q}^2}{2} - \frac{1}{q^2} \right)$$

the on-shell action becomes

$$S[q_{cl}] = \frac{1}{2} q_{cl} \dot{q}_{cl} \Big|_0^\infty + \text{finite}$$

Due to the form of potential, $q \rightarrow \infty$ and $\dot{q} \rightarrow \text{constant}$.

Similar to $w \rightarrow \infty$ to the form of dilaton potential, leading to $S \rightarrow \infty$ in BH case.

The variation

$$\delta S = \frac{\partial L}{\partial \dot{q}} \delta q \Big|_0^\infty + \text{EOM} \neq 0$$

since $q_{t_f \rightarrow \infty} \rightarrow \infty$.

In BH: coefficient falling faster than field variation.

Choice 1: bounded momentum, discrete q

With (q, V_λ) :

$$q|\mu\rangle = \mu|\mu\rangle,$$

$$V_\lambda|\mu\rangle = |\mu - \lambda\rangle$$

Choice 1: bounded momentum, discrete q

With (q, V_λ) :

$$q|\mu\rangle = \mu|\mu\rangle,$$

$$V_\lambda|\mu\rangle = |\mu - \lambda\rangle$$

$$H = \frac{2 - V_\lambda - V_{-\lambda}}{2\lambda^2} + \frac{1}{q^2}$$

Choice 1: bounded momentum, discrete q

With (q, V_λ) :

$$q|\mu\rangle = \mu|\mu\rangle, \quad V_\lambda|\mu\rangle = |\mu - \lambda\rangle$$

$$H = \frac{2 - V_\lambda - V_{-\lambda}}{2\lambda^2} + \frac{1}{q^2}$$

Effective H becomes

$$H = \frac{\sin^2(\lambda p)}{\lambda^2} + \left(\frac{V_{-\lambda}}{i\lambda} [\sqrt{q}, V_\lambda] + [\sqrt{q}, V_\lambda] \frac{V_{-\lambda}}{i\lambda} \right)^4$$

where we used Thiemann's regularization and a symmetrization

$$\frac{1}{\sqrt{q}} = \frac{2}{i\lambda} V_{-\lambda} \{ \sqrt{q}, V_\lambda \}.$$

Choice 1: bounded momentum, discrete q

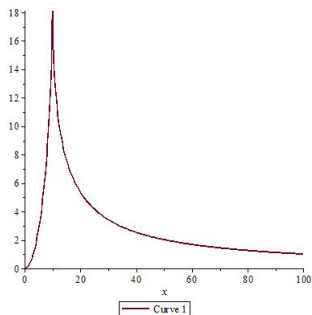
This

$$H = \frac{\sin^2(\lambda p)}{\lambda^2} + \left(\frac{V_{-\lambda}}{i\lambda} [\sqrt{q}, V_\lambda] + [\sqrt{q}, V_\lambda] \frac{V_{-\lambda}}{i\lambda} \right)^4$$

doesn't seem to solve

$$S[q_{cl}] = \frac{1}{2} q_{cl} \dot{q}_{cl} \Big|_0^\infty + \dots \rightarrow \infty$$

since



Choice 1: bounded momentum, discrete q

This

$$H = \frac{\sin^2(\lambda p)}{\lambda^2} + \left(\frac{V_{-\lambda}}{i\lambda} [\sqrt{q}, V_\lambda] + [\sqrt{q}, V_\lambda] \frac{V_{-\lambda}}{i\lambda} \right)^4$$

doesn't seem to solve

$$S[q_{cl}] = \frac{1}{2} q_{cl} \dot{q}_{cl} \Big|_0^\infty + \dots \rightarrow \infty$$

For the same reason,

$$\delta S = \frac{\partial L}{\partial \dot{q}} \delta q \Big|_0^\infty + \text{EOM} \neq 0$$

Choice 1: bounded momentum, discrete q

This

$$H = \frac{\sin^2(\lambda p)}{\lambda^2} + \left(\frac{V_{-\lambda}}{i\lambda} [\sqrt{q}, V_\lambda] + [\sqrt{q}, V_\lambda] \frac{V_{-\lambda}}{i\lambda} \right)^4$$

doesn't seem to solve

$$S[q_{cl}] = \frac{1}{2} q_{cl} \dot{q}_{cl} \Big|_0^\infty + \dots \rightarrow \infty$$

For the same reason,

$$\delta S = \frac{\partial L}{\partial \dot{q}} \delta q \Big|_0^\infty + \text{EOM} \neq 0$$

Apparently only advantage: V can be represented using Thiemann's trick.

Choice 2: bounded q , discrete momentum

With (U_μ, p) :

$$U_\mu|\lambda\rangle = \lambda|\lambda - \mu\rangle,$$

$$p|\lambda\rangle = \lambda|\lambda\rangle$$

Choice 2: bounded q , discrete momentum

With (U_μ, p) :

$$U_\mu|\lambda\rangle = \lambda|\lambda - \mu\rangle,$$

$$p|\lambda\rangle = \lambda|\lambda\rangle$$

$$H = \frac{p^2}{2} + V(U_\mu)$$

Choice 2: bounded q , discrete momentum

With (U_μ, p) :

$$U_\mu|\lambda\rangle = \lambda|\lambda - \mu\rangle,$$

$$p|\lambda\rangle = \lambda|\lambda\rangle$$

$$H = \frac{p^2}{2} + V(U_\mu)$$

Likely to bound potential and thus avoid the on-shell action divergence.

Choice 2: bounded q , discrete momentum

With (U_μ, p) :

$$U_\mu|\lambda\rangle = \lambda|\lambda - \mu\rangle, \quad p|\lambda\rangle = \lambda|\lambda\rangle$$

$$H = \frac{p^2}{2} + V(U_\mu)$$

Likely to bound potential and thus avoid the on-shell action divergence.
Also since if classical q brought to finite values, $\delta q_{t \rightarrow \infty} \rightarrow 0$.

Choice 2: bounded q , discrete momentum

With (U_μ, p) :

$$U_\mu|\lambda\rangle = \lambda|\lambda - \mu\rangle,$$

$$p|\lambda\rangle = \lambda|\lambda\rangle$$

$$H = \frac{p^2}{2} + V(U_\mu)$$

Likely to bound potential and thus avoid the on-shell action divergence.
Also since if classical q brought to finite values, $\delta q_{t \rightarrow \infty} \rightarrow 0$.
May solve both problems: no need for a counter-term.

Choice 2: bounded q , discrete momentum

With (U_μ, p) :

$$U_\mu|\lambda\rangle = \lambda|\lambda - \mu\rangle, \quad p|\lambda\rangle = \lambda|\lambda\rangle$$

$$H = \frac{p^2}{2} + V(U_\mu)$$

Likely to bound potential and thus avoid the on-shell action divergence.
Also since if classical q brought to finite values, $\delta q_{t \rightarrow \infty} \rightarrow 0$.
May solve both problems: no need for a counter-term.

However, hard to see how $V = \frac{1}{q^2}$ can be represented in this case...

Choice 2: bounded q , discrete momentum

Thiemann's trick with “wrong polarization” of variables: how

$$\frac{1}{q^2} \stackrel{?}{=} \{f(U_\mu), g(p)\}$$

Choice 2: bounded q , discrete momentum

Thiemann's trick with “wrong polarization” of variables: how

$$\frac{1}{q^2} \stackrel{?}{=} \{f(U_\mu), g(p)\}$$

Classical choices may be available e.g.

$$\frac{1}{\sqrt{i\mu}} \left\{ \sqrt{\ln(U_\mu)}, p \right\} = \frac{1}{\sqrt{q}}$$

but seem unsuitable for representation.

Choice 2: bounded q , discrete momentum

Thiemann's trick with “wrong polarization” of variables: how

$$\frac{1}{q^2} \stackrel{?}{=} \{f(U_\mu), g(p)\}$$

Classical choices may be available e.g.

$$\frac{1}{\sqrt{i\mu}} \left\{ \sqrt{\ln(U_\mu)}, p \right\} = \frac{1}{\sqrt{q}}$$

but seem unsuitable for representation.

Semi-good news: dilaton potential in some models is linear.

Choice 2: bounded q , discrete momentum

Thiemann's trick with “wrong polarization” of variables: how

$$\frac{1}{q^2} \stackrel{?}{=} \{f(U_\mu), g(p)\}$$

Classical choices may be available e.g.

$$\frac{1}{\sqrt{i\mu}} \left\{ \sqrt{\ln(U_\mu)}, p \right\} = \frac{1}{\sqrt{q}}$$

but seem unsuitable for representation.

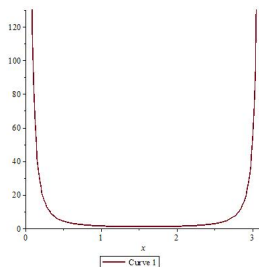
Semi-good news: dilaton potential in some models is linear.

Bad news: not all the saddle point problems mentioned are due to dilaton potential.

A heuristic model

Based on the insight from previous tries: A heuristic model bounding potential

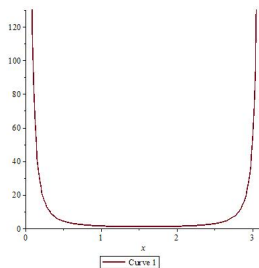
$$H_{eff} = \frac{p^2}{2} + \frac{\mu^2}{\sin^2(\mu q)}$$



A heuristic model

Based on the insight from previous tries: A heuristic model bounding potential

$$H_{eff} = \frac{p^2}{2} + \frac{\mu^2}{\sin^2(\mu q)}$$



Since the potential (and thus q) is bounded, $\delta q_{t \rightarrow \infty} \rightarrow 0$. Also the boundary term of the on-shell action $\left. \frac{1}{2} q_{cl} \dot{q}_{cl} \right|_0^\infty$ is finite.

Some lessons for the BH from the toy model

Most important problem with BH seems to be w

$$w(\Phi) = \int^{\Phi} d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

$$Q(\Phi) = \int^{\Phi} d\tilde{\Phi} U(\tilde{\Phi})$$

$$\partial_r \Phi = e^{-Q(\Phi)}$$

Some lessons for the BH from the toy model

Most important problem with BH seems to be w

$$w(\Phi) = \int^{\Phi} d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

$$Q(\Phi) = \int^{\Phi} d\tilde{\Phi} U(\tilde{\Phi})$$

$$\partial_r \Phi = e^{-Q(\Phi)}$$

What matters: dilaton potential, fall-off of dilaton and if Φ is bounded (similar to potential in toy model).

Some lessons for the BH from the toy model

Most important problem with BH seems to be w

$$w(\Phi) = \int^{\Phi} d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

$$Q(\Phi) = \int^{\Phi} d\tilde{\Phi} U(\tilde{\Phi})$$

$$\partial_r \Phi = e^{-Q(\Phi)}$$

What matters: dilaton potential, fall-off of dilaton and if Φ is bounded (similar to potential in toy model).

May have dilemma in choice of polymerization:

Some lessons for the BH from the toy model

Most important problem with BH seems to be w

$$w(\Phi) = \int^{\Phi} d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

$$Q(\Phi) = \int^{\Phi} d\tilde{\Phi} U(\tilde{\Phi})$$

$$\partial_r \Phi = e^{-Q(\Phi)}$$

What matters: dilaton potential, fall-off of dilaton and if Φ is bounded (similar to potential in toy model).

May have dilemma in choice of polymerization:

- Φ related to entropy and area etc. Bounding Φ or making it discrete seem to have important differences.

Some lessons for the BH from the toy model

Most important problem with BH seems to be w

$$w(\Phi) = \int^{\Phi} d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

$$Q(\Phi) = \int^{\Phi} d\tilde{\Phi} U(\tilde{\Phi})$$

$$\partial_r \Phi = e^{-Q(\Phi)}$$

What matters: dilaton potential, fall-off of dilaton and if Φ is bounded (similar to potential in toy model).

May have dilemma in choice of polymerization:

- Φ related to entropy and area etc. Bounding Φ or making it discrete seem to have important differences.
- A physically reasonable choice may not be easy to represent.

Some lessons for the BH from the toy model

Most important problem with BH seems to be w

$$w(\Phi) = \int^{\Phi} d\tilde{\Phi} V(\tilde{\Phi}) e^{Q(\tilde{\Phi})}$$

$$Q(\Phi) = \int^{\Phi} d\tilde{\Phi} U(\tilde{\Phi})$$

$$\partial_r \Phi = e^{-Q(\Phi)}$$

What matters: dilaton potential, fall-off of dilaton and if Φ is bounded (similar to potential in toy model).

May have dilemma in choice of polymerization:

- Φ related to entropy and area etc. Bounding Φ or making it discrete seem to have important differences.
 - A physically reasonable choice may not be easy to represent.
-

Well-posedness of (or access to) semiclassical approximation, related to choice of polymerization which is related to thermodynamics (not surprisingly)?