

New action for simplicial gravity

Curvature and relation to Regge calculus

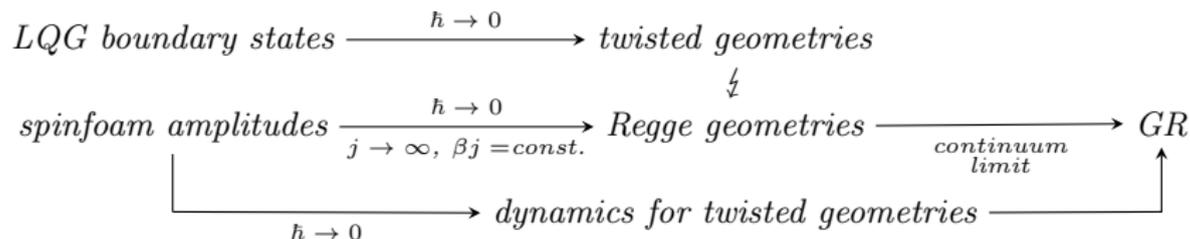
Wolfgang Wieland

Institute for Gravitation and the Cosmos, Penn State

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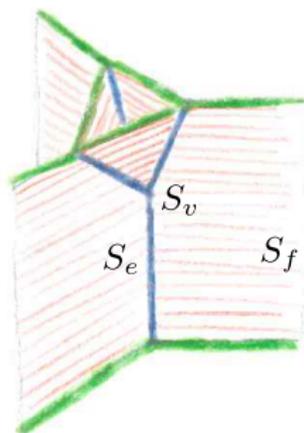
20 February 2015

What is the semi-classical limit for all spins?



For large spins (large distances) and small Barbero–Immirzi parameter we seem to get the Regge action. What do we get for small spins—short distances—high energies?

The semi-classical limit of covariant LQG for arbitrary values of j and β should give a theory of discretized gravity in terms of Ashtekar–Barbero variables. Can we find such a classical theory without knowing the exact quantum theory behind?



- A spinfoam model assigns amplitudes A_e, A_f, A_v, \dots to the elementary building blocks of the simplicial complex.
- In the semi-classical limit these amplitudes turn into action functionals:
 $A_e \propto e^{iS_e}, A_f \propto e^{iS_f}, A_v \propto e^{iS_v}, \dots$
- The desired action will be of the form:
 $S_{\text{spinfoam}} = \sum_e S_e + \sum_f S_f + \sum_v S_v + \dots$

Main message: Covariant LQG suggests a new action for simplicial gravity with spinors as the fundamental configuration variables: The theory has a Hamiltonian and local gauge symmetries. Generic solutions represent twisted geometries, but the solution space contains also Regge configurations.

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References:

*ww, [New action for simplicial gravity in four dimensions](#), Class. Quant. Grav. 32 (2015), [arXiv:1407.0025](#).

*ww, [One-dimensional action for simplicial gravity in three dimensions](#), Phys. Rev. D 90 (2014), [arXiv:1402.6708](#).

*ww, [Twistorial phase space for complex Ashtekar variables](#), Class. Quant. Grav. 29 (2012), [arXiv:1107.5002](#).

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Worldline action for simplicial gravity

The BF action is topological, and determines the symplectic structure of the theory:

$$S_{\text{BF}}[\Sigma, A] = \int_{\mathcal{M}} \underbrace{\frac{1}{2\ell_{\text{P}}^2} \left(* \Sigma_{\alpha\beta} - \frac{1}{\beta} \Sigma_{\alpha\beta} \right)}_{\Pi_{\alpha\beta}} \wedge F^{\alpha\beta}[A]. \quad (1)$$

General relativity follows from the simplicity constraints added to the action:

$$\Sigma^{\alpha\beta} \wedge \Sigma^{\mu\nu} \propto \epsilon^{\alpha\beta\mu\nu}. \quad (2)$$

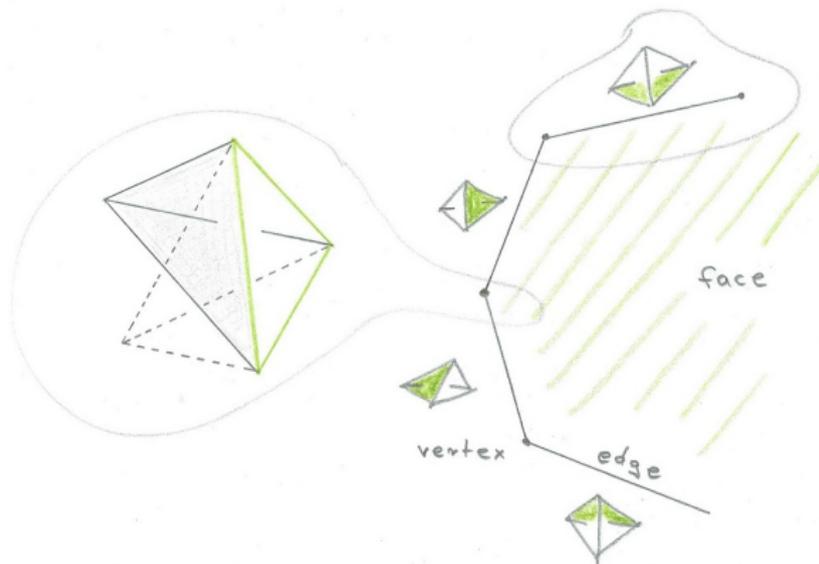
With the solutions:

$$\Sigma^{\alpha\beta} = \begin{cases} \pm e_{\alpha} \wedge e_{\beta}, \\ \pm * (e_{\alpha} \wedge e_{\beta}). \end{cases} \quad (3)$$

Notation:

- $\alpha, \beta, \gamma \dots$ are internal Lorentz indices.
- Σ^{α}_{β} is an $\mathfrak{so}(1, 3)$ -valued two-form.
- A^{α}_{β} is an $SO(1, 3)$ connection, with $F^{\alpha}_{\beta} = dA^{\alpha}_{\beta} + A^{\alpha}_{\mu} \wedge A^{\mu}_{\beta}$ denoting its curvature.
- e^{α} is the tetrad, diagonalizing the four-dimensional metric $g = \eta_{\alpha\beta} e^{\alpha} \otimes e^{\beta}$.
- $\ell_{\text{P}}^2 = 8\pi/G$, and β is the Barbero-Immirzi parameter, $\hbar = 1 = c$.

Simplicial discretization



Faust:

Das Pentagramma macht dir Pein?
Ei sage mir, du Sohn der Hölle,
Wenn das dich bannt, wie kamst du denn herein?
Wie ward ein solcher Geist betrogen?

Mephistopheles:

Beschaut es recht! es ist nicht gut gezogen:
Der eine Winkel, der nach außen zu,
Ist, wie du siehst, ein wenig offen.

Faust:

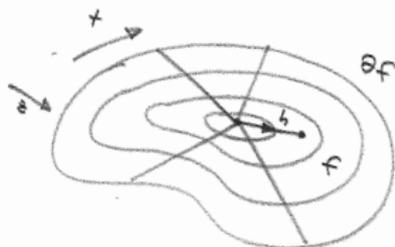
The pentagram prohibits thee?
Why, tell me now, thou Son of Hades,
If that prevents, how cam'st thou in to me?
Could such a spirit be so cheated?

Mephistopheles:

Inspect the thing: the drawing's not completed.
The outer angle, you may see,
Is open left—the lines don't fit it.

- Step 1: Discretize the action:

$$S_{\text{BF}}[\Sigma, A] = \int_{\mathcal{M}} \Pi_{\alpha\beta} \wedge F^{\alpha\beta} \approx \sum_{f:\text{faces}} \int_{\tau_f} \Pi_{\alpha\beta} \int_f F^{\alpha\beta} \equiv \sum_{f:\text{faces}} S_f.$$



- Step 2: Employ the non-Abelian Stoke's theorem:

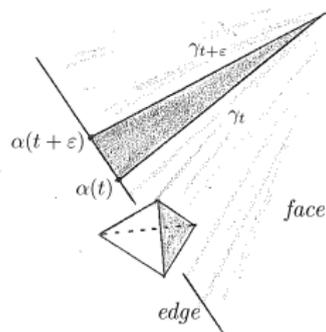
$$F_f = \int_f h^{-1} F h = \oint_{\partial f} h^{-1} D h.$$

- Step 3: Define the smeared flux:

$$\Pi_f = \int_{\tau_f} h^{-1} \Pi h.$$

- Step 4: Contract the two formulae in a common frame:

$$S_f = - \oint_{\partial f} dt \left[h_{\gamma_t(1)}^{-1} \frac{D}{dt} h_{\gamma_t(1)} \right]_{\alpha\beta} \Pi_f^{\alpha\beta}(t).$$



- Step 5: Introduce spinors to diagonalize both holonomies and fluxes:

$$\Pi_f^{\alpha\beta}(t) = \frac{1}{2} \bar{\epsilon}^{\bar{A}\bar{B}} \omega_f^{(A}(t) \pi_f^{B)}(t) + \text{cc.},$$

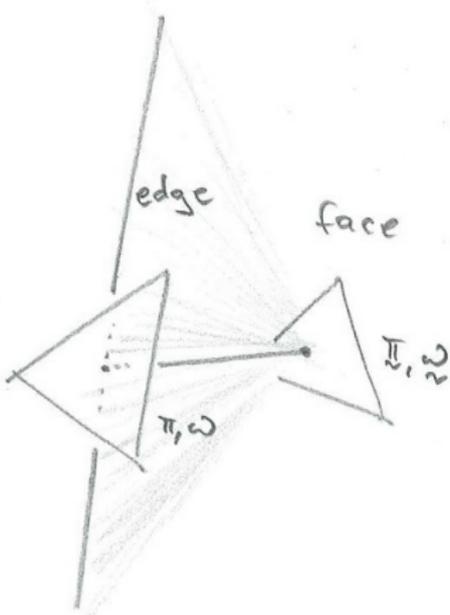
$$[h_{\gamma t}]^A_B = \text{Pexp}\left(-\int_{\gamma t} A\right)^A_B = \frac{\omega_f^A(t) \pi_B^f(t) - \pi_f^A(t) \omega_B^f(t)}{\sqrt{E_f(t)} \sqrt{\underline{E}_f(t)}}.$$

We also need the area-matching constraint:

$$\Delta_f := \pi_A^f \omega_f^A - \pi_A^f \omega_f^A \equiv \underline{E}_f(t) - E_f(t).$$

Putting the pieces together yields the face action:

$$S_f[Z, \underline{Z}, A, \zeta] = \oint_{\partial f} dt \left[\pi_A \frac{D}{dt} \omega^A - \underline{\pi}_A \frac{d}{dt} \underline{\omega}^A - \zeta \Delta \right] + \text{cc.} \quad (5)$$



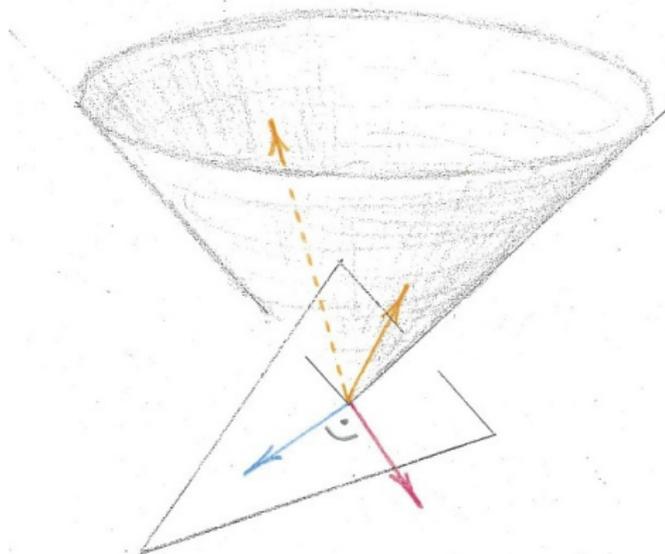
Geometric interpretation of the spinors

We define the complex null tetrad

$$\begin{aligned} \ell^\alpha &= i\pi^A \bar{\pi}^{\bar{A}}, & k^\alpha &= i\omega^A \bar{\omega}^{\bar{A}}, \\ \frac{1}{2}(x^\alpha + iy^\alpha) &= m^\alpha = i\omega^A \bar{\pi}^{\bar{A}}, & \bar{m}^\alpha &= i\pi^A \bar{\omega}^{\bar{A}}. \end{aligned}$$

Area, and plane of the triangle:

$$(\beta + i) Ar = \beta \ell_P^2 \pi_A \omega^A, \quad \Sigma_{\alpha\beta} \propto x_{[\alpha} y_{\beta]} \quad (6)$$



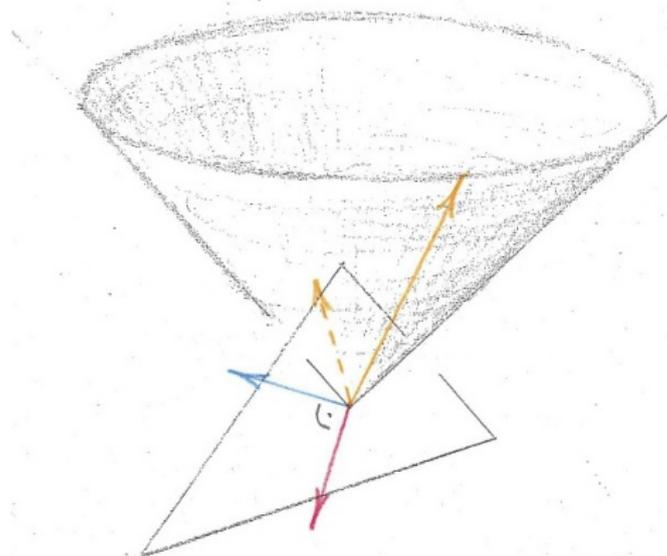
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The area-matching constraint Δ generates the transformations:

$$\pi^A \rightarrow e^z \pi^A, \quad \omega^A \rightarrow e^{-z} \omega^A, \quad z \in \mathbb{C}. \quad (7)$$



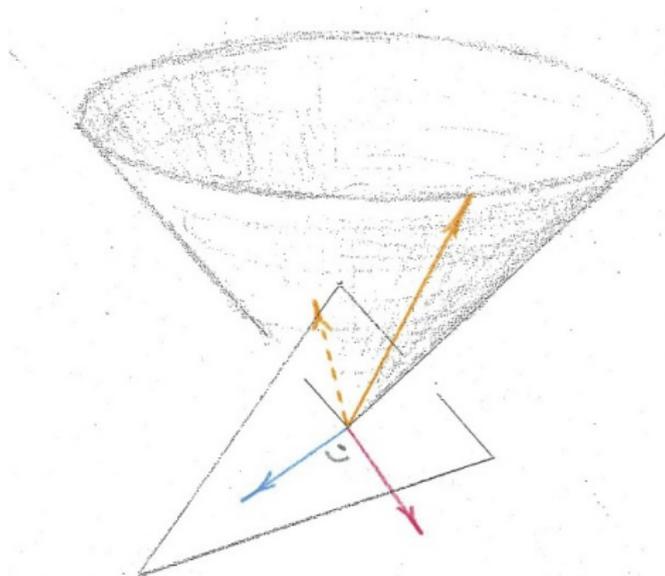
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Rotations around the z -axis:

$$\pi^A \rightarrow e^{-\frac{i\varphi}{2}} \pi^A, \quad \omega^A \rightarrow e^{\frac{i\varphi}{2}} \omega^A, \quad \varphi \in [0, 4\pi). \quad (8)$$



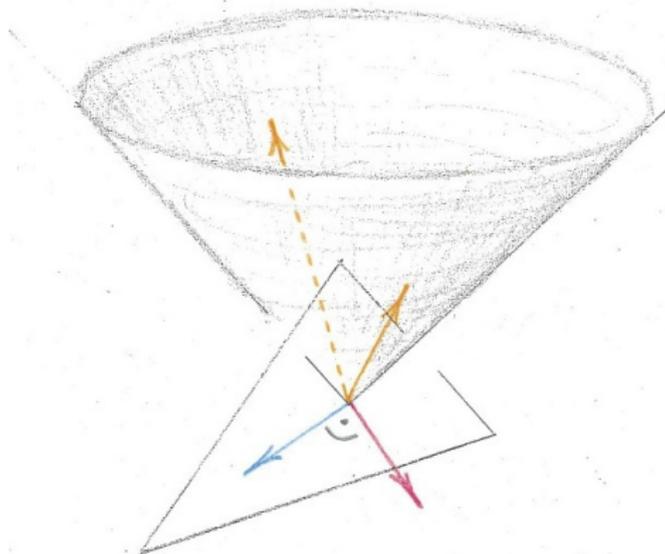
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Boosts into the z -direction:

$$\pi^A \rightarrow e^{-\frac{\xi}{2}} \pi^A, \quad \omega^A \rightarrow e^{\frac{\xi}{2}} \omega^A, \quad \xi \in \mathbb{R}. \quad (9)$$



Instead of discretizing the quadratic simplicity constraints

$$\Sigma_{\alpha\beta} \wedge \Sigma_{\mu\nu} \propto \epsilon_{\alpha\beta\mu\nu}, \quad (10)$$

we will use the linear simplicity constraints:

For a tetrahedron T_e (dual to an edge e) there exist an internal future-oriented four-vector n_e^α such that the fluxes through the four bounding triangles τ_f (dual to a face f : $e \subset \partial f$) annihilate n_e^α :

$$\int_{\tau_f} \Sigma_{\alpha\beta} n_e^\beta = 0. \quad (11)$$

The spinorial parametrization turns the simplicity constraints into the following complex conditions:

$$V_f = \frac{i}{\beta + i} \pi_A^f \omega_f^A + \text{cc.} \stackrel{!}{=} 0, \quad (12a)$$

$$W_{ef} = n_e^{A\bar{A}} \pi_A^f \bar{\omega}_A^f \stackrel{!}{=} 0. \quad (12b)$$

Adding the simplicity constraints

- The simplicity constraints reduce the $SO(1, 3)$ spin connection $A^\alpha{}_\beta$ to the $SU(2)_n$ Ashtekar–Barbero connection:

$$\mathcal{A}^\alpha = n^\mu \left[\frac{1}{2} \epsilon_{\mu\nu}{}^{\alpha\rho} A^\nu{}_\rho + \beta A^\alpha{}_\mu \right]. \quad (13)$$

- We introduce Lagrange multipliers $\lambda \in \mathbb{R}$ and $z \in \mathbb{C}$ and get the following constrained action for each face in the discretization:

$$S_{\text{face}}[Z, \underline{Z}|\zeta, z, \lambda|\mathcal{A}, n] = \oint_{\partial f} \left(\pi_A \mathcal{D}\omega^A - \underline{\pi}_A d\underline{\omega}^A - \zeta (\underline{\pi}_A \underline{\omega}^A - \pi_A \omega^A) + \right. \\ \left. - \frac{\lambda}{2} \left(\frac{i}{\beta + i} \pi_A \omega^A + \text{cc.} \right) - z n^{A\bar{A}} \pi_A \bar{\omega}_{\bar{A}} \right) + \text{cc.}, \quad (14)$$

where $\mathcal{D}\pi^A = d\pi^A + \mathcal{A}^\alpha \tau^A{}_{B\alpha} \pi^B$ is the $SU(2)_n$ covariant differential.

- **Problem:** There is no term in the action that would determine the t -dependence of the normal n_e^α along the edges $e(t)$.
- We now have to make a proposal.

Four-dimensional closure constraint

Any proposal for the dynamics of the time normals must respect the closure constraint at the vertices (four-simplices):

We define the four-momenta:

$$p_\alpha^e = g n_\alpha^e \text{Vol}(e). \quad (15)$$

At every four simplex we have the closure constraint:

$$\sum_{\substack{\text{outgoing edges } e \\ \text{at } v}} p_\alpha^e = \sum_{\substack{\text{incoming edges } e \\ \text{at } v}} p_\alpha^e. \quad (16)$$

The constant g is dimensionful:

$$[g] = \left[\frac{\Lambda}{8\pi G} \right] = \frac{\text{mass}}{\text{volume}} \quad (17)$$

Remarks:

- $\text{Vol}(e) \propto \frac{2}{9} n_\alpha \epsilon^{\alpha\beta\mu\nu} L_\beta^1 L_\mu^2 L_\nu^3$, with e.g.: $L_\alpha^1 = -\tau^{AB} \omega_A^{f1} \pi_B^{f1} + \text{cc}$.
- In a locally flat geometry, the closure constraint follows from the vanishing of torsion:

$$T^\alpha = D e^\alpha = 0 \Rightarrow \frac{1}{3!} \epsilon_{\alpha\rho\mu\nu} D(e^\rho \wedge e^\mu e^\nu) = 0 \Rightarrow \sum_{\substack{\text{edges } e \\ \text{at } v}} \pm_e p_\alpha^e = 0.$$

Any proposal for the dynamics of the time-normals

- *must respect the four-dimensional closure constraint, and*
- *be consistent with all symmetries of the action.*

The following action fulfills these requirements:

$$S_{\text{edge}}[X, p|N, \text{Vol}(e)] = \int_e \left(p_\alpha dX^\alpha - \frac{N}{2} (g^{-1} p_\alpha p^\alpha + g \text{Vol}^2(e)) \right). \quad (18)$$

We just need an additional boundary term at the vertices:

$$S_{\text{vertex}}[Y_v, \{X_{ev}\}_{e \ni v}, \{v_{ev}\}_{e \ni v}] = \sum_{e: e \ni v} (Y_v^\alpha - X_{ev}^\alpha) v_\alpha^{ev}. \quad (19)$$

Where N is a Lagrange multiplier imposing the mass-shell condition:

$$C := \frac{1}{2} (g^{-1} p_\alpha p^\alpha + g \text{Vol}^2(e)) \stackrel{!}{=} 0. \quad (20)$$

Putting the pieces together – defining the action

Adding the face, edge and vertex contributions gives us a proposal for an action for discretized gravity in first-order variables:

$$\begin{aligned} S_{\text{spinfoam}} = & \sum_{f:\text{faces}} S_{\text{face}} [Z_f, \underline{Z}_f | \zeta_f, z_f, \lambda_f | \mathcal{A}_{\partial f}, n_{\partial f}] + \\ & + \sum_{e:\text{edges}} S_{\text{edge}} [X_e, p_e | N_e, \text{Vol}(e)] + \\ & + \sum_{v:\text{vertices}} S_{\text{vertex}} [Y_v, \{X_{ev}\}_{e \ni v}, \{v_{ev}\}_{e \ni v}]. \end{aligned} \quad (21)$$

Notation:

- Z_f and \underline{Z}_f are the twistors $Z_f : \partial f \rightarrow \mathbb{T} \simeq \mathbb{C}^4$ parametrizing the $SL(2, \mathbb{C})$ holonomy-flux variables.
- ζ_f, λ_f and z_f are Lagrange multipliers imposing the area-matching constraint and simplicity constraints respectively.
- \mathcal{A} is the $SU(2)_n$ Ashtekar-Barbero connection along the edges of the discretization.
- n denotes the time normal of the elementary tetrahedra.
- p_e is the volume-weighted time-normal, of the tetrahedron dual to the edge e .
- $\text{Vol}(e)$ denotes the corresponding three-volume.
- N is a Lagrange multiplier imposing the mass-shell condition $C = 0$.

■ A dictionary:

| | | |
|--------------------|---|-------------------------------|
| spinfoam formalism | - | auxiliary particles |
| tetrahedra | - | particles |
| four-simplices | - | interaction vertices |
| three-volume | - | mass |
| tetrahedral shapes | - | internal $SU(2)$ DOF |
| torsion=0 | - | conservation of four-momentum |

Is this a reasonable model for discretized gravity?

- 1 **The Equations of motion generate twisted geometries:** Every triangle has a unique area, but the shape of a triangle depends on whether we compute it from the metric in one adjacent four-simplex or the other.
- 2 **Relation to Regge calculus:** We can restrict ourselves to Regge-like solutions.
- 3 **The model has curvature:** There is a deficit angle once we go around a triangle.

Regge solutions

The Hamiltonian:

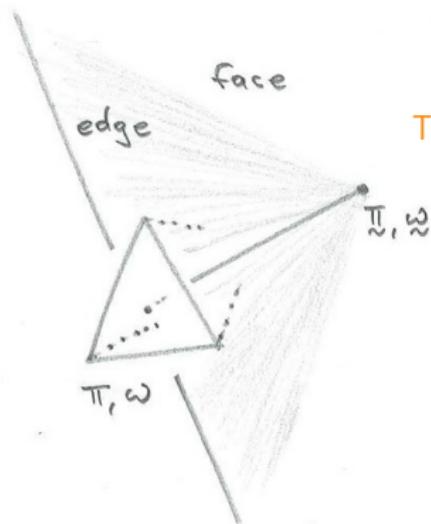
$$H = \mathcal{A}^\alpha G_\alpha + \sum_{f:\partial f \supset e} \left(\zeta^f \Delta_f + \bar{\zeta}^f \bar{\Delta}_f + z^f W_{ef} + \bar{z}^f \bar{W}_{ef} + \lambda^f V_f \right) + NC, \quad (22)$$

generates the t -evolution along the edges of the discretization:

$$\frac{d}{dt} \omega_f^A = \{H, \omega_f^A\}. \quad (23)$$

The fundamental Poisson brackets are:

$$\begin{aligned} \{p_\alpha, X^\beta\} &= \delta_\alpha^\beta, \\ \{\pi_A^f, \omega_{f'}^B\} &= +\delta_{ff'} \delta_A^B, \\ \{\underline{\pi}_A^f, \underline{\omega}_{f'}^B\} &= -\delta_{ff'} \delta_A^B. \end{aligned}$$



$$H = \mathcal{A}^\alpha G_\alpha + \sum_{f:\partial f \supset e} \left(\zeta^f \Delta_f + \bar{\zeta}^f \bar{\Delta}_f + z^f W_{ef} + \bar{z}^f \bar{W}_{ef} + \lambda^f V_f \right) + NC. \quad (24)$$

- The Hamiltonian preserves all constraints for $z_f = 0$.
- The W_{ef} simplicity constraint is second class, all other constraints first class.
- There are no secondary constraints.
- $\zeta_f = 0$ wlog.

$$H = \mathcal{A}^\alpha G_\alpha + \sum_{f:\partial f \supset e} \lambda^f V_f + NC. \quad (25)$$

Relevant constraints of the system:

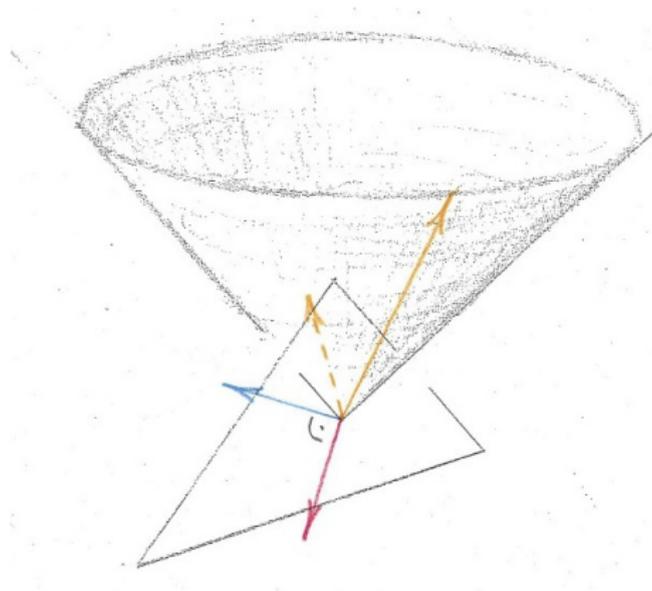
- mass-shell: $C = \frac{1}{2} \left(g^{-1} p_\alpha p^\alpha + g \text{Vol}^2 \right)$
- first-class simplicity: $V = \frac{i}{\beta+1} \pi_A \omega^A + \text{cc.}$
- Gauß constraint: $G_\alpha = - \sum_{f:\partial f \subset e} L_\alpha^f$ generates $SU(2)_n$ transformations, with $L_\alpha^f = -\tau^{AB} \pi_A^f \omega_B^f + \text{cc.}$, and $\mathfrak{su}(2)_n$ generators $\tau_\alpha : [\tau_\alpha, \tau_\beta] = \epsilon_{\alpha\beta}{}^\mu \tau_\mu$.

Action of the first-class simplicity constraints

The first-class simplicity constraints $V = 0$ generates a four-screw:

$$\{V, \omega^A\} = \frac{i}{\beta + i} \omega^A, \quad \{V, \pi^A\} = -\frac{i}{\beta + i} \pi^A.$$

A combination of a rotation and a boost preserving the triangle's plane:



*F Hellmann and W Kamiński, [Holonomy spin foam models: Asymptotic geometry of the partition function](#), JHEP 1310 (2013), [arXiv:1307.1679](#).

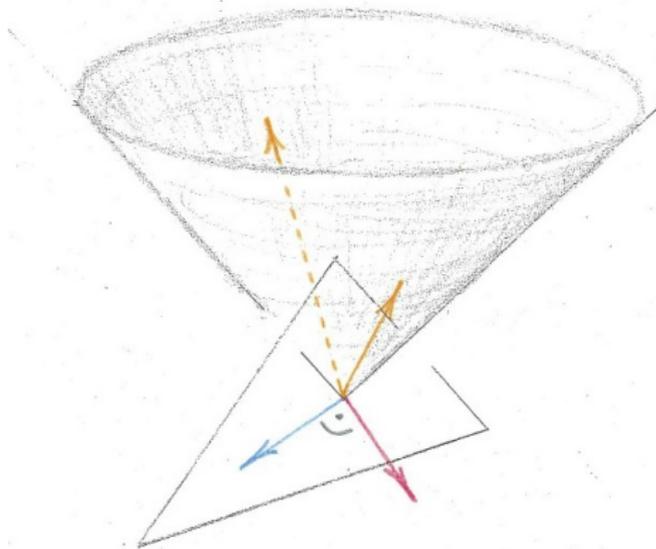
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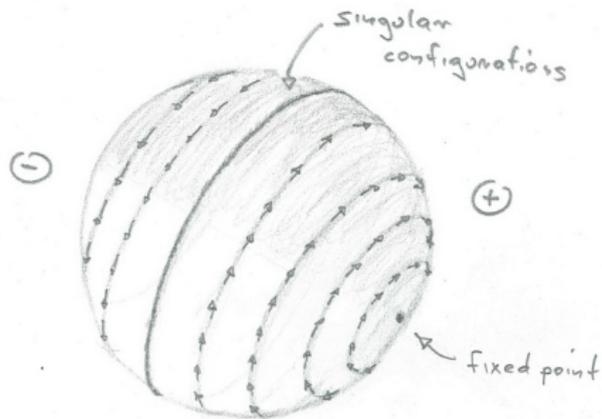


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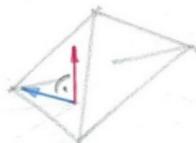
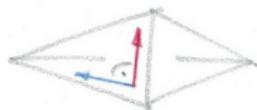
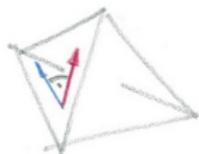
Action of the mass-shell condition

Volume flow in the shape space of all tetrahedra with fixed areas:



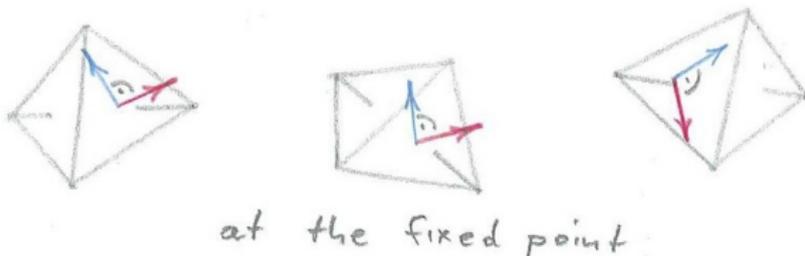
- The simplicity constraints impose that the $\Sigma_{\alpha\beta}$ fluxes define planes in internal Minkowski space.
- The Gauß constraint G_α tells us that these planes close to form a tetrahedron.
- The mass-shell condition generates a globale rotation plus a shear plus a $U(1)$ rotation in the plane of every triangle.

$$C = \frac{1}{2}(g^{-1}p_\alpha p^\alpha + g\text{Vol}^2), \quad \text{with: } \text{Vol}^2 \propto \frac{2}{9}n_\alpha \epsilon^{\alpha\beta\mu\nu} L_\beta^1 L_\mu^2 L_\nu^3.$$



Restriction to stable tetrahedra

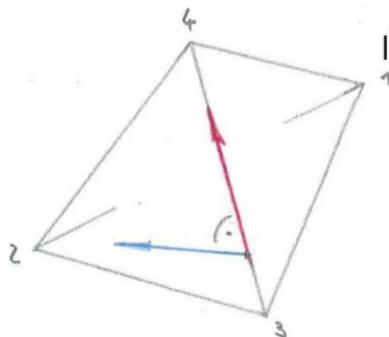
- We restrict ourselves to tetrahedra that are stable under the volume flow:



- The mass shell condition generates residual $U(1)$ transformation of the spinors in the triangles:

$$\pi^A \rightarrow e^{-\frac{i\varphi}{2}} \pi^A, \quad \omega^A \rightarrow e^{+\frac{i\varphi}{2}} \omega^A. \quad (26)$$

- We can tune these angles in such a way that they cancel the unwanted rotation from the simplicity constraints.
- We are then left with a pure boost.



It works as follows (for e.g. the spinors in the 1-plane):

- We align the dyade in the 1-plane with the (34)-edge,
- and require that the Hamiltonian preserves this additional condition.

$$H = \mathcal{A}^\alpha G_\alpha + \sum_{f=1}^4 \lambda^f V_f + NC. \quad (27)$$

- This fixes the Lagrange multiplier λ^f in terms of N :

$$\lambda^1(N) = \frac{g\ell_P^2}{4} (1 + \beta^2) \frac{\text{Vol}^2}{\sin^2 \vartheta_{12}} \frac{\text{Ar}_2 + \text{Ar}_1 \cos \vartheta_{12}}{\text{Ar}_1 \text{Ar}_2} N \quad (28)$$

- There are three possible choices to align the spinors to an edge. The result (28) is independent of this ambiguity.

Remark:

ϑ_{IJ} is the dihedral angle, Vol denotes the volume and Ar_I is the area of the I -th triangle.

Our alignment brings the evolution equations into a simple form:

$$\frac{\nabla}{dt}\omega_f^A = \frac{d}{dt}\omega_f^A + \Gamma^A{}_B\omega_f^B = +\frac{\xi_f}{2}\omega_f^A, \quad (29a)$$

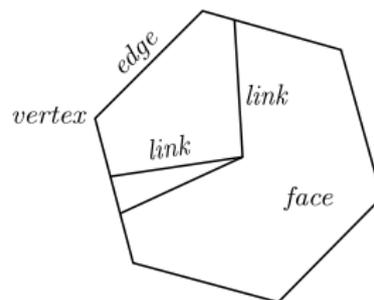
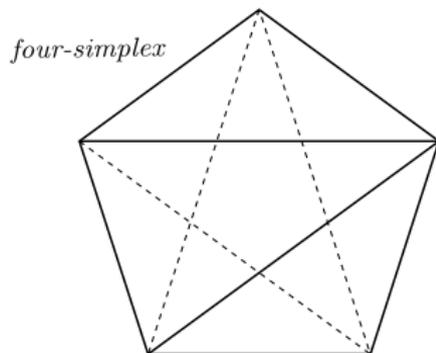
$$\frac{\nabla}{dt}\pi_f^A = \frac{d}{dt}\pi_f^A + \Gamma^A{}_B\pi_f^B = -\frac{\xi_f}{2}\pi_f^A, \quad (29b)$$

Geometric interpretation:

- $\Gamma \in \mathfrak{su}(2)_n$ is the Levi-Civita connection along the edges.
- $\xi_f \in \mathbb{R}$ measures the extrinsic curvature in the face f .
- The parallel transport around the face is a pure boost:

$$\begin{aligned} [h_f]^A{}_B &= \left[\text{Pexp} \left(- \oint_{\partial f} dt \Gamma \right) \right]^A{}_B = \\ &= \frac{1}{\pi_C \omega^C} \left[e^{-\frac{1}{2} \oint_{\partial f} dt \xi} \omega^A \pi_B + e^{+\frac{1}{2} \oint_{\partial f} dt \xi} \pi^A \omega_B \right] \end{aligned} \quad (30)$$

Deficit angle and extrinsic curvature



Inter-tetrahedral angles:

$$\cosh \Xi_{vf} = -\eta^{\mu\nu} n_{\mu}^e n_{\nu}^{e'}, \quad \text{with: } e \cap e' = v, \text{ and: } e, e' \subset \partial f. \quad (31)$$

Deficit angle around a triangle:

$$\Xi_f := \sum_{v: \text{vertices in } f} \Xi_{vf} = \oint_{\partial f} dt \xi. \quad (32)$$

The on-shell action is the Regge action

We evaluate the on-shell action for volume-stable geometries.

- The action consists of a symplectic potential plus constraints.
- The constraints vanish on-shell.
- The symplectic potential $p_\alpha dX^\alpha$ does not contribute either, because of:

$$\int_e p_\alpha dX^\alpha \stackrel{\text{EOM}}{=} p_\alpha \left[X^\alpha|_{e(1)} - X^\alpha|_{e(0)} \right], \quad \text{and} \quad \sum_{\substack{\text{edges } e \\ \text{at } v}} \pm_e p_\alpha^e = 0 \quad (33)$$

- All contributions come from the symplectic potential for the spinors.

Regge action at the fixed point of the volume flow

$$S_{\text{spinfoam}}[\underline{\pi}, \underline{\omega}, \underline{p}, \underline{X}] \stackrel{\text{EOM}}{=} \sum_{f:\text{faces}} \oint_{\partial f} \pi_A^f d\omega_f^A + \text{cc.} \stackrel{\text{EOM}}{=} \frac{1}{2} \sum_{f:\text{faces}} \pi_A^f \omega_f^A \Xi_f + \text{cc.} =$$
$$\stackrel{\text{EOM}}{=} \frac{1}{2} \sum_{f:\text{faces}} \frac{(\beta + i)}{\beta \ell_P^2} \text{Ar}_f \Xi_f + \text{cc.} = \frac{1}{8\pi G} \sum_{f:\text{faces}} \text{Ar}_f \Xi_f = S_{\text{Regge}}[\{\ell_b\}_{b:\text{bones}}].$$

Solutions of the equations of motion extremize the spinfoam action, hence they also bring the Regge action to an extremum.

Conclusion

General picture: The simplicial edges turn into the worldlines of a system of auxiliary particles scattering in a flat auxiliary manifold. Every tetrahedron carries a conserved four-momentum. Its norm is not mass but volume.

Results:

- Generic solutions represent twisted geometries that are the boundary data of loop quantum gravity.
- Regge configurations appear at the fixed point of the volume flow, where the on-shell action $\mathcal{S}_{\text{spinfoam}}$ turns into the Regge action $\mathcal{S}_{\text{Regge}}$.

- Role of local Lorentz invariance: The addition of the $p_\alpha dX^\alpha$ term breaks local $SL(2, \mathbb{C})$ invariance down to the little group $SU(2)_n$.
- What is the physical role of the X^α -background geometry with flat Minkowski metric $\eta_{\alpha\beta}$? Is there a relation to teleparallelism?
- We have only shown local existence of Regge-like solutions. Open problem: Find explicit solutions that triangulate physical (Ricci flat) spacetime geometries.

- **Quantum kinematics (simple problem):** The instantaneous Hilbert space is the Hilbert space of projected spin network functions.
Area \leftrightarrow norm of the Pauli–Lubanski vector. Quantization of area \leftrightarrow quantization of spin in the auxiliary particle model.
- **Quantum dynamics (hard problem):** Take the spinfoam action and reformulate loop quantum gravity as a one-dimensional QFT over the edges of the discretization. The spinfoam amplitudes turn into the S -matrix amplitudes of an auxiliary worldline model.

*S Alexandrov and ER Livine , [SU\(2\) loop quantum gravity seen from covariant theory](#) , Phys. Rev. D 67 (2003), arXiv:gr-qc/0209105.

Thank you for your attention
